

2011 April 13

(1)

Mixing Length Theory (MLT) (CH 5.1)

How to quantify the turbulent convection, and determine the convection flux.

MLT: to simplify the process, assuming the convection parcel travels a characteristic time " ℓ ", the mixing length, before it lose identity as the parcel break-up and merge with the surrounding fluid.

A typical " ℓ " is a fraction of λ_p (pressure scale height)

We need to solve a time dependent energy equation and momentum equation because $\mathbf{U} \neq 0$.

Energy Equation: Radiative Leakage (CH 5.1.2)

Assuming non-adiabatic, as bubble rises, heat transfer cools the bubble, thus reduce the strength of convection

If non-heat transfer, or adiabatic, \Rightarrow super-convection

$$\frac{dQ'}{dt} = -\nabla \cdot F_{rad}$$

P.T

$$dQ' = C_p P dT'$$

$$C_p - C_v = \frac{P}{\rho T} \frac{\chi_T^2}{\chi_P^2} \quad \text{--- (3.9a)}$$

$$C_p - C_v = \frac{N_A K}{\mu} \quad (\text{ideal gas}) \quad \text{--- (3.4a)}$$

$$C_v = \frac{3 N_A K}{2 \mu} \left(\frac{\delta - 7\beta}{\beta} \right) \quad \text{--- (3.15)}$$

$$C_v = \frac{3 N_A K}{2 \mu} \quad (\text{ideal gas})$$

$$C_p = \frac{5}{2} \frac{N_A K}{\mu} \quad (\text{ideal gas})$$

erg g⁻¹ K⁻¹

(2)

(Continued)

$$\left(\frac{\partial T'}{\partial t} \right) = - \frac{1}{\rho C_p} \nabla \cdot \mathbf{F}_{\text{rad}} \quad \dots \quad (5.12)$$

$$\mathbf{F}_{\text{rad}} = -K \nabla T \quad \dots \quad (5.13)$$

$$K = \frac{4\alpha c T^3}{3k\rho} \quad \dots \quad (5.14)$$

K: (radiation) diffusion constant

$$\left(\frac{\partial T'}{\partial t} \right) = \frac{K}{\rho C_p} \nabla^2 T = \frac{4\alpha c T^3}{3k\rho^2 C_p} \nabla^2 T \quad \dots \quad (5.15)$$

$$\nu_T = \frac{4\alpha c T^3}{3k\rho^2 C_p} \quad \dots \quad (5.16)$$

 ν_T : thermal diffusivity (due to radiation) : cm^2/s

$$\left(\frac{\partial T'}{\partial t} \right) = \nu_T \nabla^2 T \quad \dots \quad (5.17)$$

Usually in MLT: $\boxed{\nabla^2 T = \frac{T - T'}{\ell^2}}$

 $\frac{\partial T'}{\partial t}$: local derivative at a fixed point; Eulerian form

Need to consider the movement of the parcel

$$\frac{DT'}{dt} = \frac{dT'}{dt}$$
 total derivative; following the parcel
 $\quad \quad \quad$: Lagrangian form

$$\frac{DT'}{dt} = \left(\frac{\partial T'}{\partial t} \right) + \vec{w} \cdot \nabla T' \quad \dots \quad (5.18)$$

 w : the parcel velocity

$$\vec{w} \cdot \nabla T' = w \frac{\partial T'}{\partial z} = w \underbrace{\left(\frac{dT'}{dz} \right)_{\text{ad}}}_{\text{describe } T' \text{ change without heat loss}} = -w \beta_{\text{ad}} T'$$

$$\frac{DT'}{dt} = \frac{\nu_T}{\rho^2} (T - T') - \beta_{\text{ad}} w \quad \dots \quad (5.19)$$

$$\Delta T = T' - T$$

(5.20)

$$\frac{DT}{Dt} = \frac{dT}{dz} \frac{dz}{dt} = -\beta w$$

adiabatic

leaking

$$\frac{D\Delta T}{Dt} = \frac{DT'}{Dt} - \frac{DT}{Dt} = (\beta - \frac{\gamma}{\kappa})w - \frac{DT}{t^2} \Delta T \quad \dots \quad (5.21)$$

This describes how temperature difference changes with time

(1) depend on how temperature changes with z

(2) depend on how radiation energy transfers

Equation of Motion (CH 5.1.3)

Body force

$$\boxed{P} P' = P$$

$$P \frac{dw}{dt} = (P - P')g$$

$$\frac{dw}{dt} = \frac{(P - P')}{P} g \quad \dots \quad (5.22)$$

α : coefficient of thermal expansion $\alpha > 0$

$$-\alpha = \left(\frac{d \ln P}{d \ln T} \right)_P = -\frac{\chi_T}{\chi_P} \quad \dots \quad (5.23)$$

$$d \ln P = \chi_P d \ln P + \chi_T d \ln T$$

$$\alpha = -\frac{\Delta P}{P} \cdot \frac{T}{\Delta T} ; \quad \alpha = 1 \text{ for ideal gas}$$

$$\frac{P' - P}{P} = \frac{\Delta P}{P} = -\alpha \frac{\Delta T}{T} = -\alpha \frac{T' - T}{T}$$

$$\frac{dw}{dt} = \frac{\alpha g}{T} \Delta T \quad \dots \quad (5.24)$$

(5.21) and (5.24) combined to determine the convection

$$\Rightarrow W(t)$$

$$\Rightarrow \Delta T(t)$$

(4)

Convective Efficiencies and Time Scales (CH 5.1.4)

A simple instability analysis of energy equation + momentum Eq.

$$\frac{D(\Delta T)}{Dt} = (\beta - \beta_{ad}) w - \frac{v_T}{\ell^2} \Delta T$$

$$\frac{dw}{dt} = \frac{\alpha g}{T} \Delta T$$

ζ : growth rate

$$\left. \begin{array}{l} \Delta T = T_0 e^{\zeta t} \\ w = w_0 e^{\zeta t} \end{array} \right\}$$

positive: grow

ζ : real

negative: damping

ζ : imaginary: oscillation

$$\frac{D^2(\Delta T)}{Dt} = (\beta - \beta_{ad}) \frac{dw}{dt} - \frac{v_T}{\ell^2} \frac{D(\Delta T)}{Dt}$$

$$\frac{T_0 \zeta^2 e^{\zeta t}}{\zeta^2 \Delta T} = \frac{\alpha g}{T} \zeta T$$

$$\frac{T_0 e^{\zeta t}}{\zeta \Delta T} \zeta$$

$$\zeta^2 + \frac{v_T}{\ell^2} - \frac{\alpha g}{T} (\beta - \beta_{ad}) = 0 \quad \dots (5.27)$$

Note: v_T , ℓ , α , g , T , β , β_{ad} - all known
This quadratic equation can be solved easily.

* Brunt - Väisälä frequency N

$$N^2 = -\frac{\alpha g}{T} (\beta - \beta_{ad}) \quad \dots (5.28)$$

$$\zeta^2 + \frac{v_T}{\ell^2} + N^2 = 0 \quad \dots (5.30)$$

ζ damping term grow or ~~oscillate~~ oscillate

$$\zeta = \frac{-\frac{v_T}{\ell^2} \pm \sqrt{\left(\frac{v_T}{\ell^2}\right)^2 - 4N^2}}{2}; \quad \zeta^2 = -N^2 \text{ (ignore damping)}$$

$N^2 < 0 \Rightarrow \beta - \beta_{ad} > 0 \Rightarrow$ convection; ζ : real

$N^2 > 0 \Rightarrow \beta - \beta_{ad} < 0 \Rightarrow \zeta$: imaginary: oscillation.

N : grow rate and/or oscillation frequency (s^{-1})

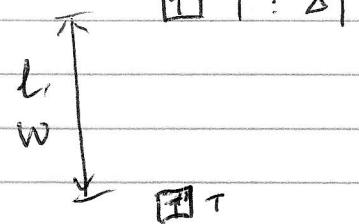
(5)

Convective Flux C CH 5.1.5)

$$F_{\text{conv}} = \rho C_p \Delta T \cdot w \quad \dots \quad (5.36)$$

energy carried \downarrow how fast

$$w = \zeta l$$



$$\frac{d\Delta T}{dt} = (\beta - \beta_{\text{adi}}) w - \frac{\nu_l}{\alpha g} f$$

$$\cdot \zeta \Delta T \frac{\zeta^2 \pi}{9g} \cdot \zeta l$$

$$\zeta^2 = -N^2 = \frac{\alpha}{T} g (\beta - \beta_{\text{adi}}) \quad \dots \quad (5.25)$$

$$\Delta T = \frac{C^2 dT}{Qg} \quad \dots \quad (5.35)$$

$$F_{\text{conv}} = \frac{\rho C_p T \zeta^3 d^2}{Qg} \quad \dots \quad (5.36)$$

$$L_{\text{conv}} = 4\pi r^2 F_{\text{conv}} \quad \dots \quad (5.37)$$

For adiabatic convection, or super-convection

$$\zeta = \sqrt{-N^2} = \sqrt{\frac{\alpha g}{T} (\beta - \beta_{\text{adi}})}$$

$$F_{\text{conv}} = \frac{\rho C_p d^2 T g^{\frac{1}{2}} \alpha^{\frac{1}{2}} (\nabla - \nabla_{\text{ad}})^{\frac{3}{2}}}{\lambda_p^{\frac{3}{2}}} \quad \dots \quad (5.38)$$

Stellar Energy Sources (CH 6)

-Self-Study-

Energy generate rate $\dot{\epsilon}$: ergs $g^{-1} s^{-1}$

(7)

Stellar Modeling (CH 7)

- putting all the physics in "analytic" format together, then find the "exact" solution

Equations of stellar structure (CH 7.1)

(1) Conservation of mass

$$\frac{dM_r}{dr} = 4\pi r^2 \rho \quad \text{or} \quad \frac{dr}{dM_r} = \frac{1}{4\pi r^2 \rho} \quad \dots (7.5)$$

(2) Conservation of Momentum

$$\frac{dp}{dr} = -\rho g_I \quad \text{or} \quad \frac{dp}{dM_r} = -\frac{GM_r}{4\pi r^4} \quad \dots (7.6)$$

(3) Conservation of Energy

$$\frac{dL_r}{dr} = 4\pi r^2 \rho \epsilon \quad \text{or} \quad \frac{dL_r}{dM_r} = \epsilon \quad \dots (7.7)$$

To find M_r , $P(r)$, $\rho(r)$, $T(r)$, $L(r)$,

need two more equations.

(4) Equation of state. ← from statistical mechanics

$$P = P(\rho, T, X) = P_0 \rho^{\chi_P} T^{\chi_T}$$

(5) Energy diffusion equations ← from radiation transfer

$$\nabla_{rad} = \frac{3}{16\pi c} \frac{PK}{T^4} \frac{L_r}{GM_r} \quad \text{if } (\nabla_{rad} < \nabla_{ad}) \quad (7.8)$$

or. $\nabla = \nabla_{ad}$ (convection) if $\nabla_{rad} > \nabla_{ad}$ $\dots (7.10)$

And constituent equations from microphysics

$$(6) \quad \kappa = K(\rho, T, X) : \left(\text{cm}^2 \text{g}^{-1} \text{s}^{-1} \right), \text{absorption coefficient}$$

atomic physics ← nuclear physics

$$(7) \quad \epsilon = \epsilon(\rho, T, X) : \left(\text{ergs g}^{-1} \text{s}^{-1} \right), \text{energy generation rate}$$

Numerical solution

ordinary

solving three-coupled first-order differential equations
It is trivial for a modern computer.
but, one has to specify the boundary condition.

(1) $r=0, Mr=0$ or at $Mr=0, r=0$

(2) $r=0, Lr=0$ or at $Mr=0, Lr=0$

(3) $r=R, P=\underline{0}$ or at $M=M_*, \underline{P=0}$
but, what is R ?

Numerical calculation (CH 7.2.2)

(1) Marching Integration Method.

Initial value problem, integrate forward
from the center, until $P=0$ - the surface.

Use "Runge - Kutta" method for integration

(2) fitting method:

Integration from both ends, joint at a point

(3) Finite difference method

Also "Newton - Raphson" or "Henyey" method

solving equations ~~on~~ a pre-constructed grid.

On each grid point, a set of linear equations
— solving a big matrix